

Modelado Parte VI

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Estudio de estabilidad

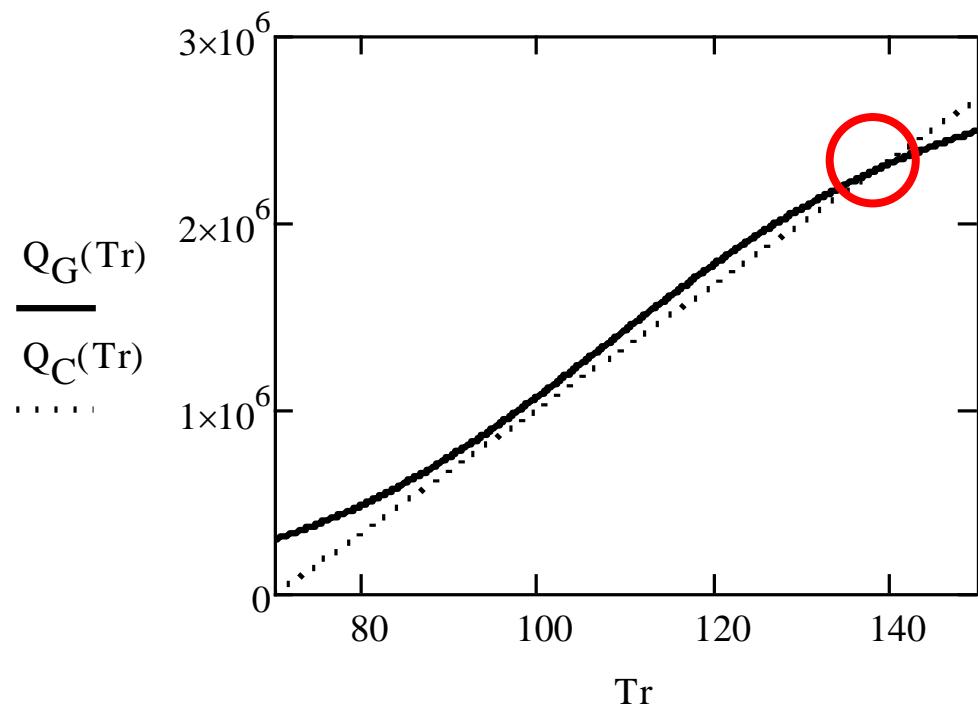
Estudio de estabilidad

Estado estacionario

$$0 = F_0 C_0 Cp_0 (T_0 - T) + V r (-\Delta H) - Q$$

$$Q_G = V r (-\Delta H) \quad r(T)$$

$$Q_C = F_0 C_0 Cp_0 (T - T_0) + Q \quad Q(T)$$

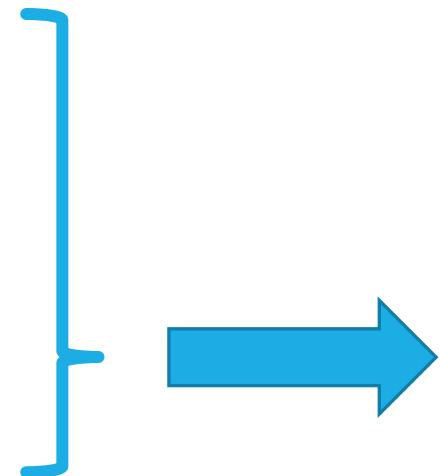


Calor generado

$$Q_G = V r (-\Delta H)$$

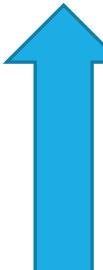
$$r = \alpha e^{-\frac{E}{RT}} C_A$$

$$0 = \frac{F_0(C_{A0} - C_A)}{V} - r$$



$$Q_G = \frac{V \alpha e^{-\frac{E}{RT}} C_{A0} (-\Delta H)}{\frac{V}{F_0} \alpha e^{-\frac{E}{RT}} + 1}$$

$$r = \frac{\alpha e^{-\frac{E}{RT}} C_{A0}}{\frac{V}{F_0} \alpha e^{-\frac{E}{RT}} + 1}$$



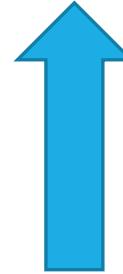
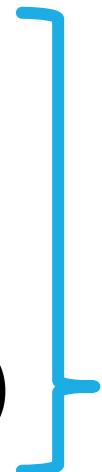
Calor consumido

$$Q_C = F_0 C_0 Cp_0 (T - T_0) + Q$$

$$Q_C = F_0 C_0 Cp_0 (T - T_0) + N_{s0} Cp_{s0} (T - T_{s0}) \left(1 - e^{-\frac{UA}{N_{s0} Cp_{s0}}} \right)$$

$$Q = UA \frac{T_s - T_{s0}}{\ln \left(\frac{T - T_{s0}}{T - T_s} \right)}$$

$$Q = N_{s0} Cp_{s0} (T_s - T_{s0})$$



$$Q = N_{s0} Cp_{s0} (T - T_{s0}) \left(1 - e^{-\frac{UA}{N_{s0} Cp_{s0}}} \right)$$

Estado estacionario

$$Q_C = F_0 C_0 Cp_0 (T - T_0) + N_{s0} Cp_{s0} (T - T_{s0}) \left(1 - e^{-\frac{UA}{N_{s0} Cp_{s0}}} \right)$$

$$Q_C = \left(F_0 C_0 Cp_0 + N_{s0} Cp_{s0} \left(1 - e^{-\frac{UA}{N_{s0} Cp_{s0}}} \right) \right) T - \left(F_0 C_0 Cp_0 T_0 + N_{s0} Cp_{s0} T_{s0} \left(1 - e^{-\frac{UA}{N_{s0} Cp_{s0}}} \right) \right)$$

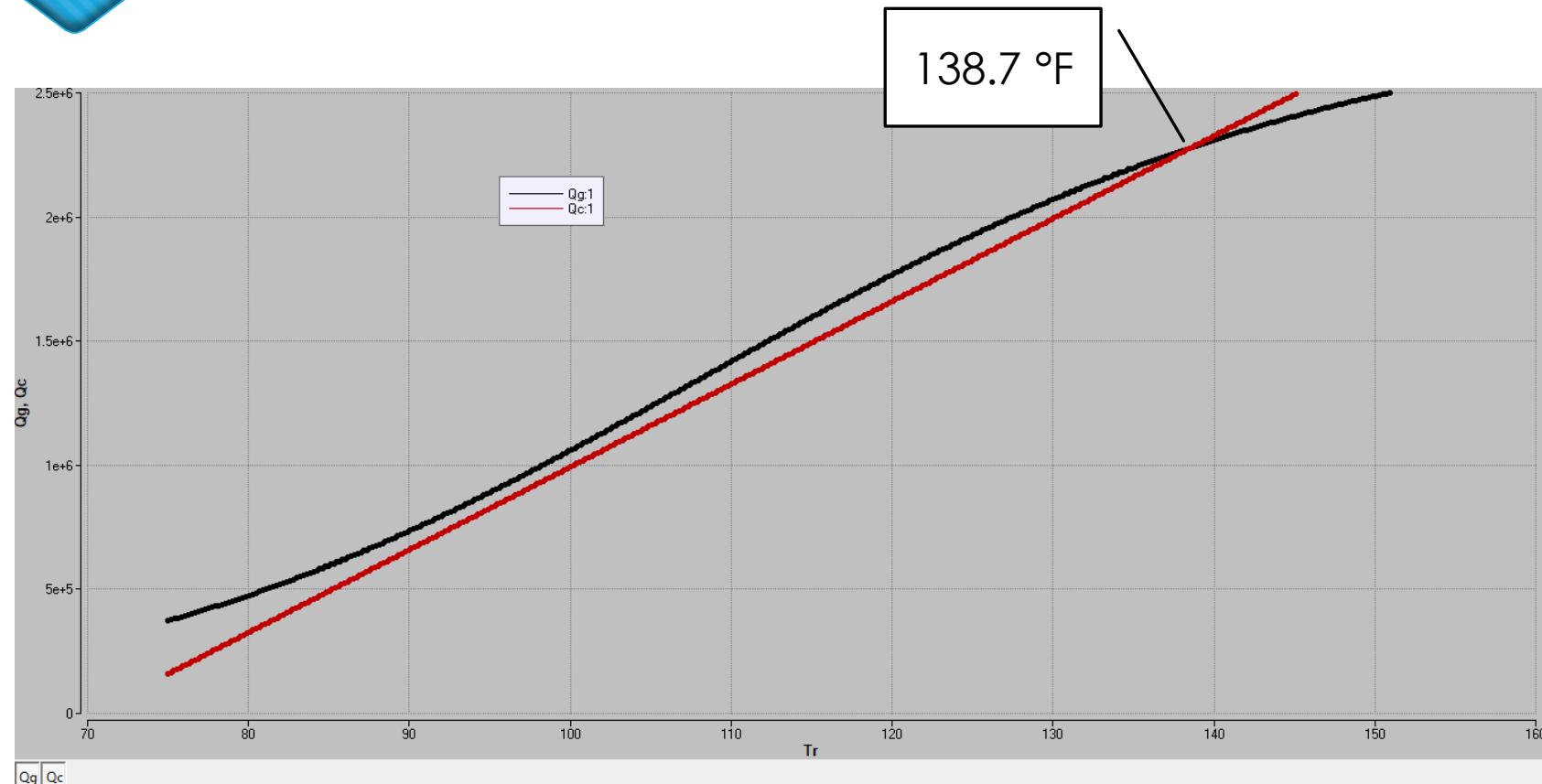
- No se puede modificar la pendiente sin modificar la distancia al origen; pero sí se puede modificar la distancia al origen sin alterar la pendiente variando T_0 y T_{s0} .
- Q_C depende de la corriente de enfriamiento, mientras que Q_G no.

Calor generado y consumido

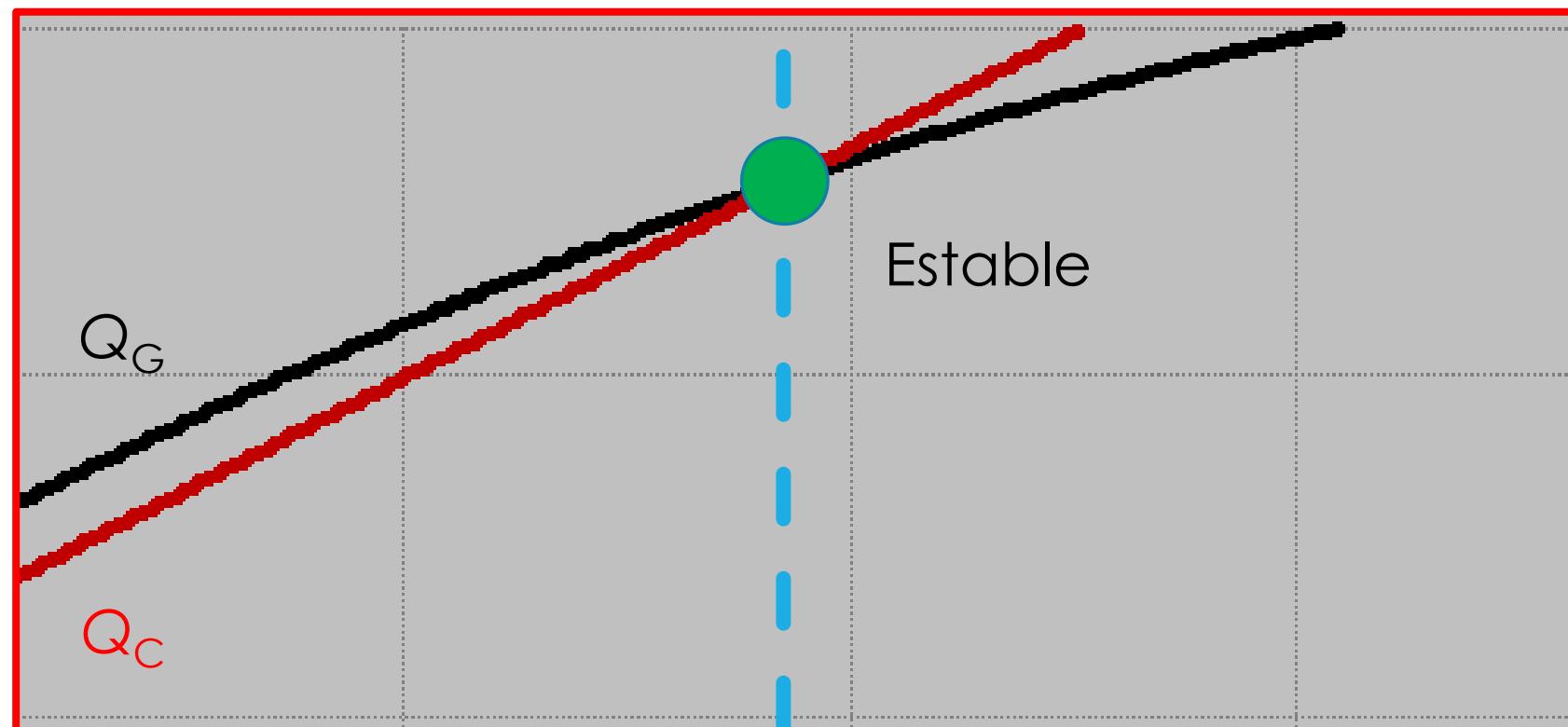
$$Q_G = \frac{V \alpha e^{-\frac{E}{RT}} C_{A0} (-\Delta H)}{\frac{V}{F_0} \alpha e^{-\frac{E}{RT}} + 1}$$

$$Q_C = F_0 C_0 Cp_0 (T - T_0) + N_{s0} Cp_{s0} (T - T_{s0}) \left(1 - e^{-\frac{UA}{N_{s0} Cp_{s0}}} \right)$$

Estado estacionario

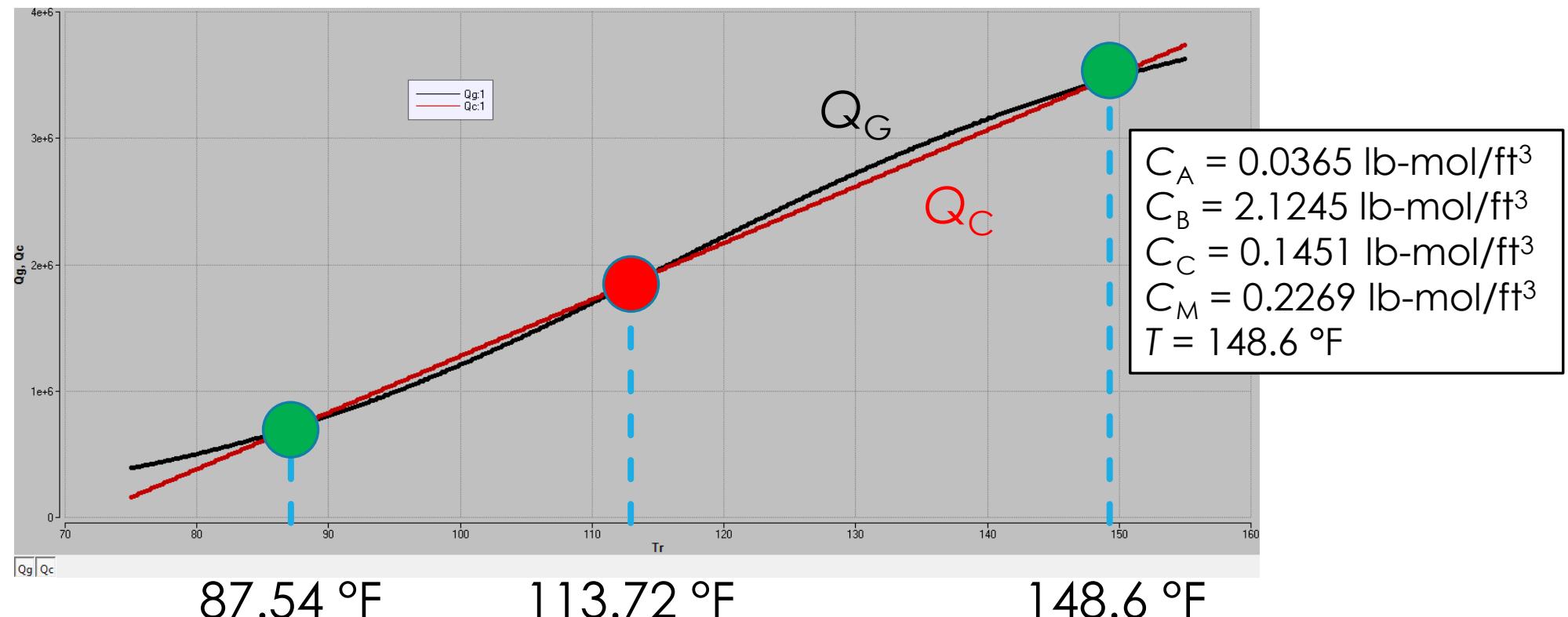


Estabilidad



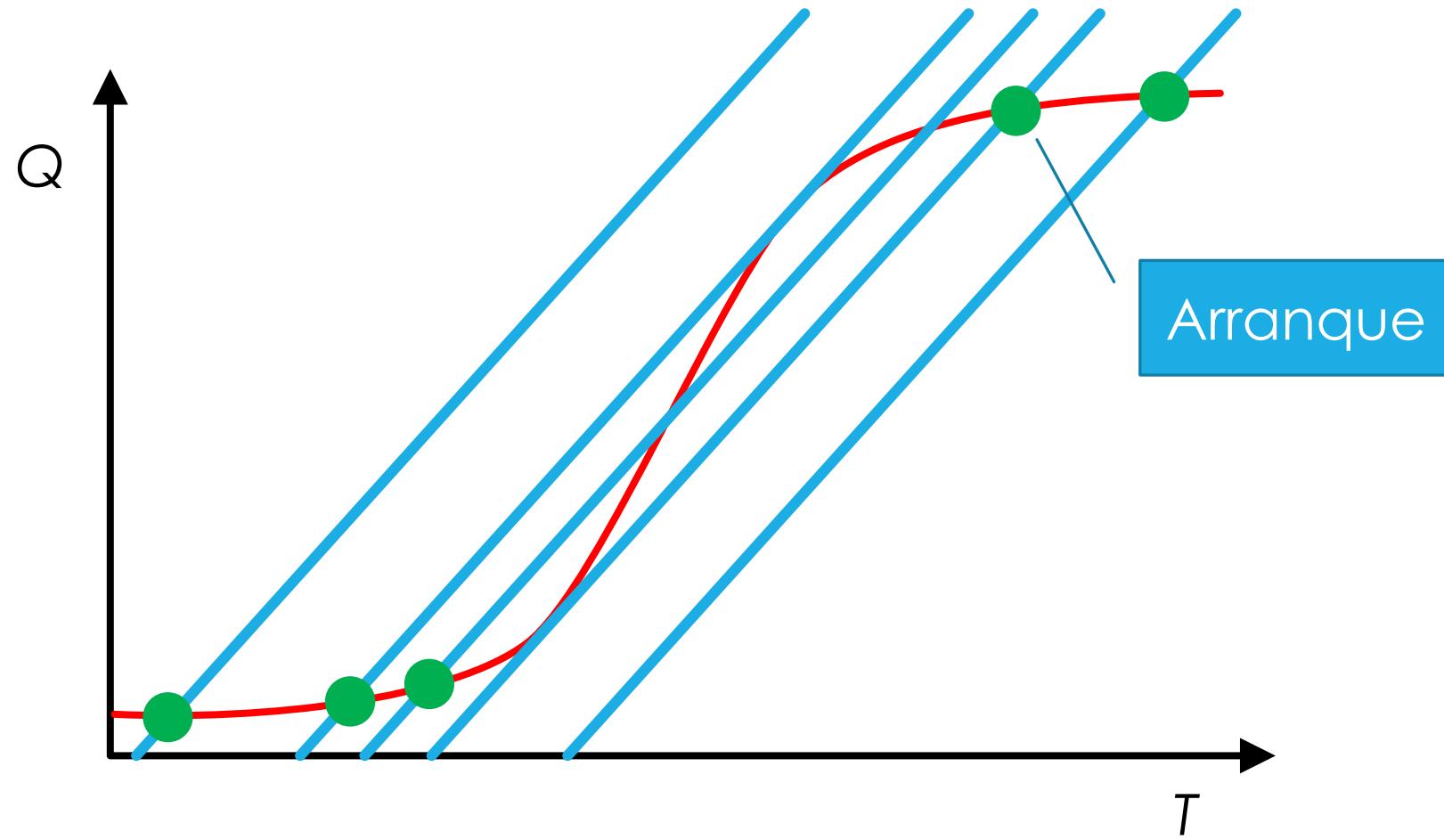
Verificar por simulación.

Estabilidad, 50 % de aumento en F_0

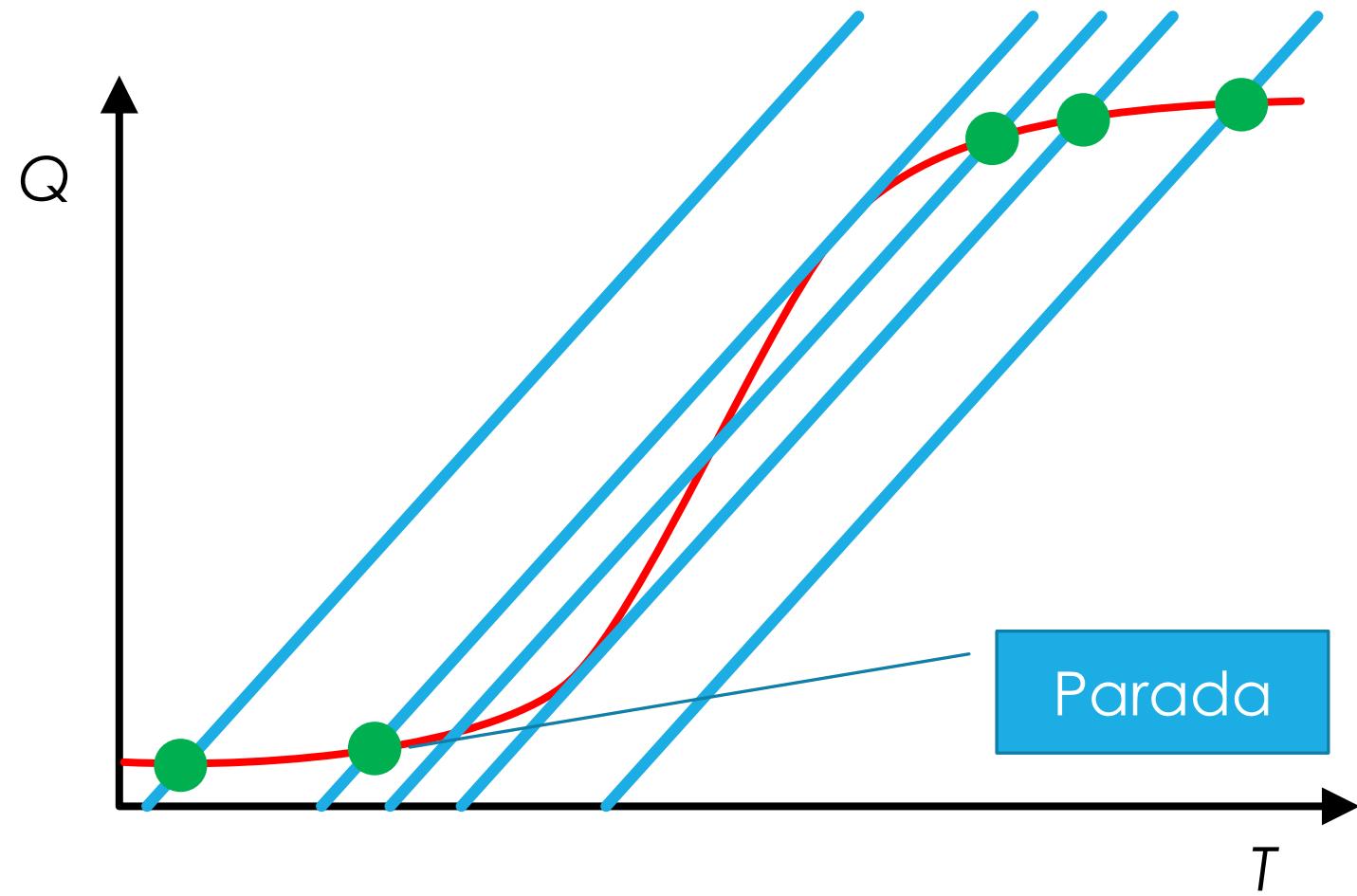


Verificar por simulación.

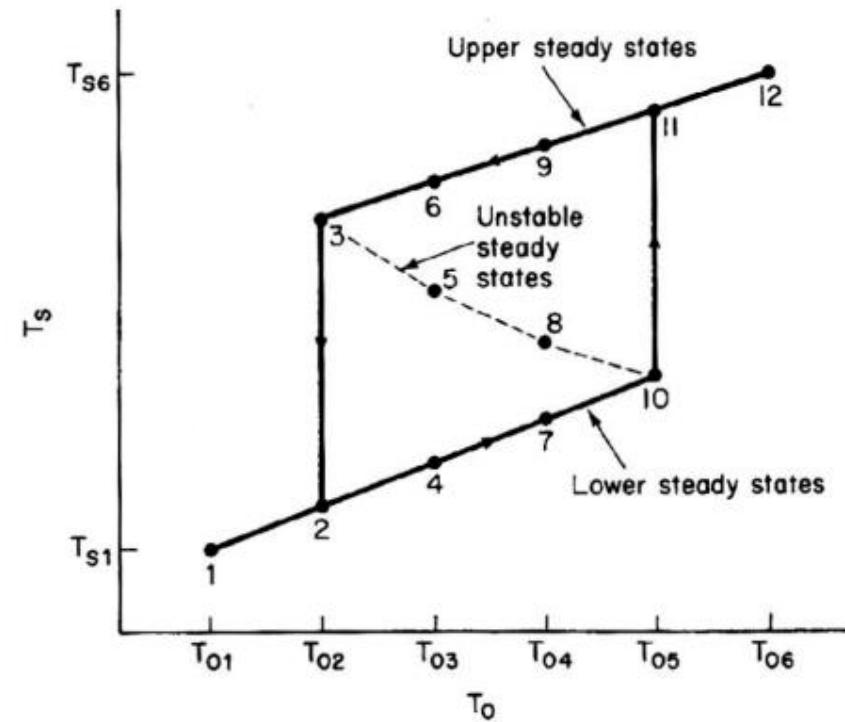
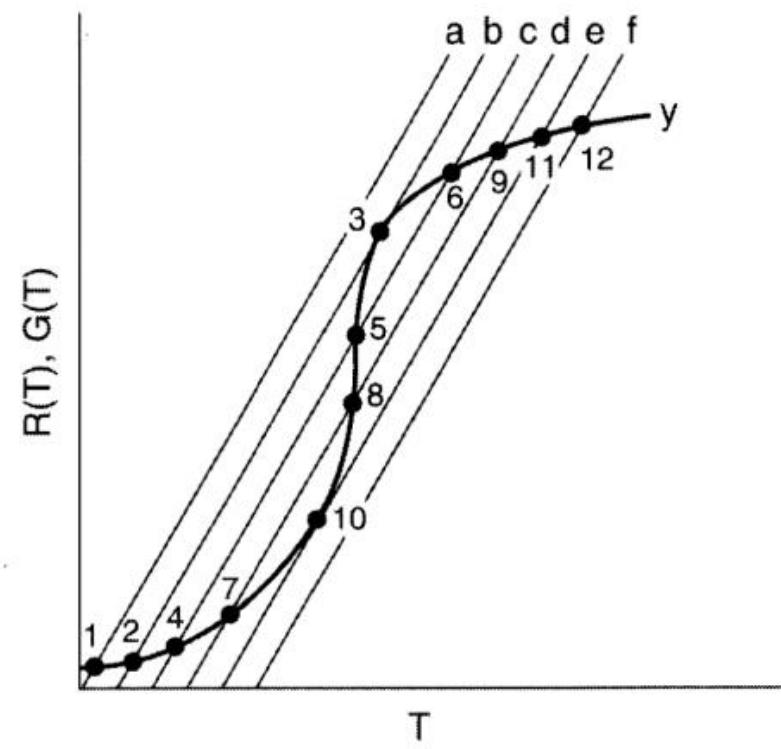
Arranque aumentando T_0



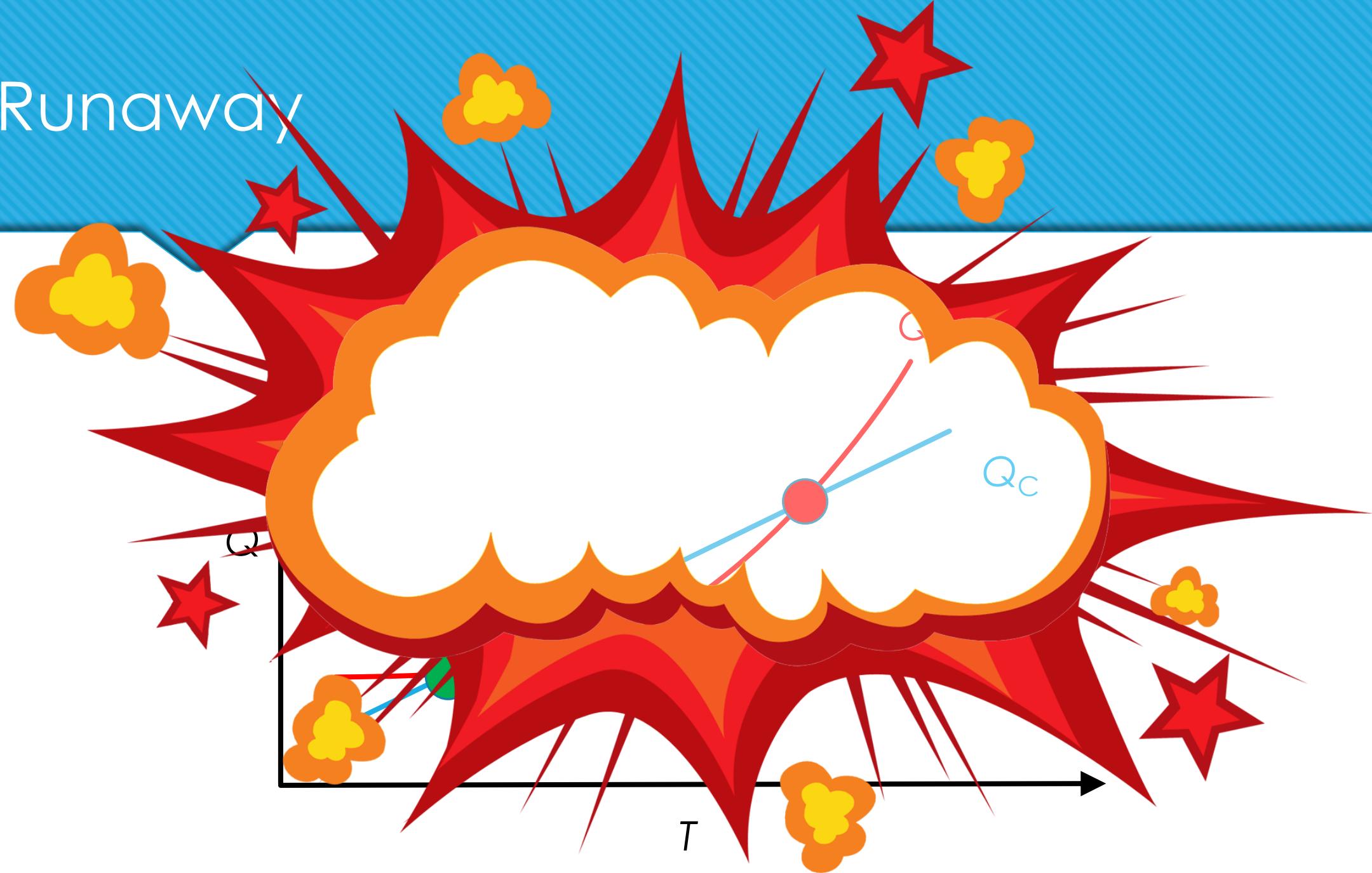
Parada disminuyendo T_0



Histéresis



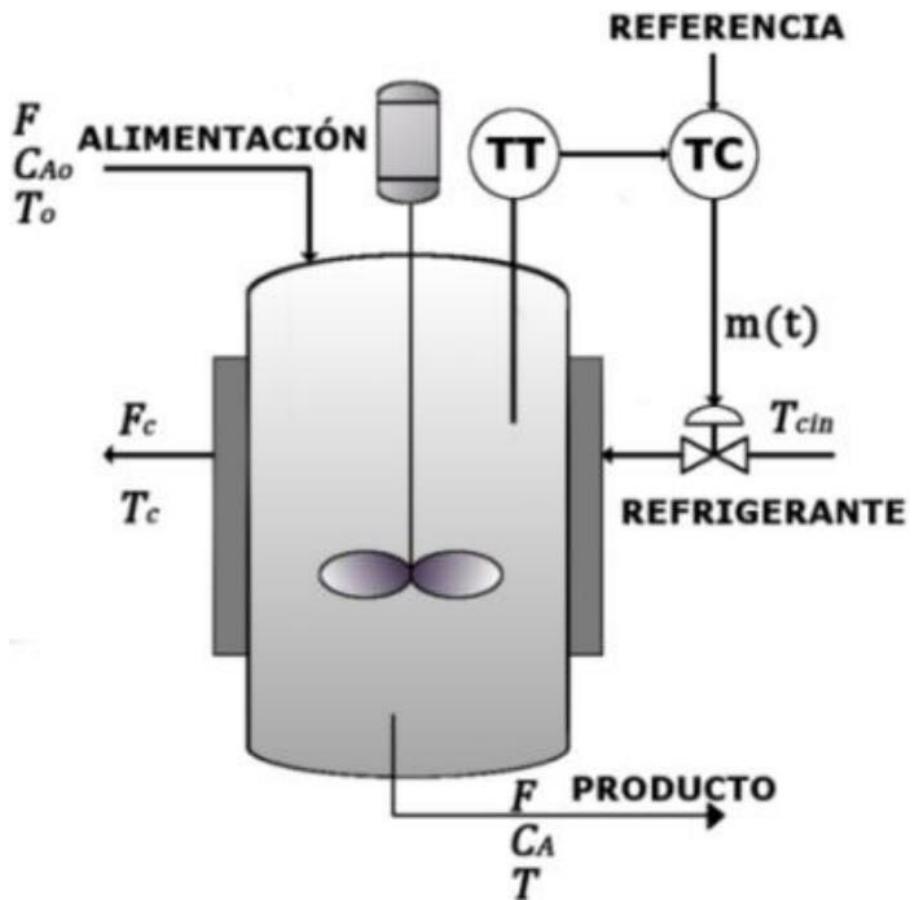
Runaway



Instalación de un controlador de temperatura

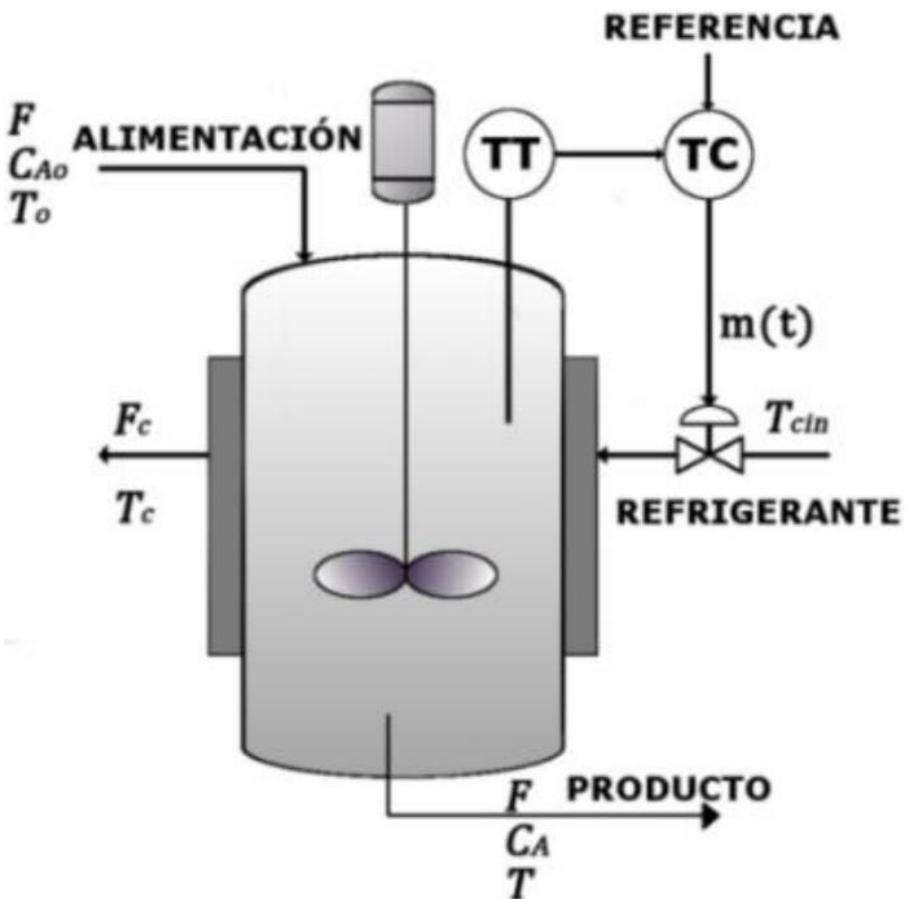
Selección de acción en modo servo

1. Acción inversa y válvula NA
2. Set point $T_{sp}(+)$
3. $T_{sp}(+) \rightarrow e(+) \rightarrow Ac(+) \rightarrow x(-) \rightarrow N_{s0}(-) \rightarrow Q(-) \rightarrow T(+)$
4. Si $T(+)$, aceptar la acción.



Selección de acción en modo regulador

1. Acción inversa y válvula NA
2. $T(+)$
3. $T(+) \rightarrow e(-) \rightarrow Ac(-) \rightarrow x(+) \rightarrow N_{s0}(+)$
 $\rightarrow Q(+) \rightarrow T(-)$
4. Si $T(-)$, aceptar la acción.



Instalación de un control PI para T

Modelo original

$$Ac = Ab + Kp \left(e + \frac{1}{\tau i} Ai \right)$$

$$e = T_{sp} - T$$

$$Ai = \int_0^t edt$$

$$x_s = \begin{cases} 1 & Ac < 0 \\ 0 & Ac > 1 \\ 1 - Ac & \text{en otro caso} \end{cases}$$

Modelo simplificado

$$\frac{dAi}{dt} = e$$

$$e = T_{sp} - T$$

$$Ac = Ab + Kp \left(e + \frac{1}{\tau i} Ai \right)$$

$$x_s = \begin{cases} 1 & Ac < 0 \\ 0 & Ac > 1 \\ 1 - Ac & \text{en otro caso} \end{cases}$$

Cálculo de N_{s0}

$$F_{s0} = C_{vs} x_s \sqrt{\frac{\Delta P_{vs}}{\rho_s / \rho_w}}$$

$$N_{s0} = \frac{F_{s0} \rho_s}{PM_s}$$

Modelo de CT

$$\frac{dAi}{dt} = e$$

$$e = T_{sp} - T$$

$$Ac = Ab + Kp \left(e + \frac{1}{\tau i} Ai \right)$$

$$x_s = \begin{cases} 1 & Ac < 0 \\ 0 & Ac > 1 \\ 1 - Ac & \text{en otro caso} \end{cases}$$

$$F_{s0} = C_{vs} x_s \sqrt{\frac{\Delta P_{vs}}{\rho_s / \rho_w}}$$

$$N_{s0} = \frac{F_{s0} \rho_s}{PM_s}$$

Parámetros en sistema inglés

- $K_p = 4.25 \times 10^{-3} \text{ } ^\circ\text{F}^{-1}$
- $A_b = 0.5$
- $\dot{\tau} = 0.152 \text{ h}$
- $T_{sp} = 138.7 \text{ } ^\circ\text{F}$
- $Ai(0) = 0$
- $\rho_s = \rho_w, \rho_s = 62.43 \text{ lb/ft}^3$
- $PM_s = 18 \text{ lb/lb-mol}$
- $\Delta P_{vs} = 4.383 \times 10^{11} \text{ lb/(ft}\cdot\text{h}^2)$.
- $C_{vs} = 8.71 \times 10^{-4} \text{ ft}^{3.5}/\text{lb}^{0.5}$

Condiciones iniciales

$$C_A = 0.0377 \text{ lb-mol/ft}^3$$

$$C_B = 2.1256 \text{ lb-mol/ft}^3$$

$$C_C = 0.1439 \text{ lb-mol/ft}^3$$

$$C_M = 0.2269 \text{ lb-mol/ft}^3$$

$$T = 138.7 \text{ } ^\circ\text{F}$$

Listado en Berkeley Madonna

```
{Reactor de propilenglicol con CT}
```

```
METHOD RK4
```

```
STARTTIME = 0
```

```
STOPTIME = 3
```

```
DT = 0.01
```

```
; Inicialización
```

```
INIT CA = 0.0377
```

```
INIT CB = 2.1256
```

```
INIT CC = 0.1439
```

```
INIT CM = 0.2269
```

```
INIT Tr = 138.7
```

```
INIT Ai = 0
```

```
; Sistema ODEs
```

```
CA' = F0*(CA0-CA)/V-r
```

```
CB' = F0*(CB0-CB)/V-r
```

```
CC' = F0*(CC0-CC)/V+r
```

```
CM' = F0*(CM0-CM)/V
```

```
Tr' = (F0*C0*Cp0*(T0-Tr)+V*r*(-DH)-Q)/(V*C*Cp)
```

```
Ai' = e
```

```
; Sistema AES
```

```
r = alpha*exp(-Ea/(Rg*(Tr+460)))*CA
```

```
Ts = Ts0+(Tr-Ts0)*(1-exp(-UA/(Ns0*Cps0)))
```

```
Q = Ns0*Cps0*(Tr-Ts0)*(1-exp(-UA/(Ns0*Cps0)))
```

```
C = CA+CB+CC+CM
```

```
Cp = (CA*CpA0+CB*CpB0+CC*CpC0+CM*CpM0)/C
```

```
C0 = CA0+CB0+CC0+CM0
```

```
Cp0 = (CA0*CpA0+CB0*CpB0+CC0*CpC0+CM0*CpM0)/C0
```

```
e = Tsp-Tr
```

```
Ac = Ab+Kp*(e+Ai/tau_i)
```

```
xs = 1-Ac
```

```
LIMIT xs >= 0
```

```
LIMIT xs <= 1
```

```
Fs0 = Cvs*xs*sqrt(DPs)
```

```
Ns0 = Fs0*rhos/PMs
```

```
; Datos  
V = 66.84
```

```
F0 = 440.63
```

```
T0 = 70
```

```
CA0 = 0.1816
```

```
CB0 = 2.2695
```

```
CC0 = 0
```

```
CM0 = 0.2269
```

```
CpA0 = 35
```

```
CpB0 = 18
```

```
CpC0 = 46
```

```
CpM0 = 19.5
```

```
Ts0 = 60
```

```
Cps0 = 18
```

```
UA = 16000
```

```
DH = -36000
```

```
alpha = 16.96E12
```

```
Ea = 32400
```

```
Rg = 1.987
```

```
Tsp = 138.7
```

```
Ab = 0.5
```

```
Kp = 4.25E-3
```

```
tau_i = 0.152
```

```
rhos = 62.43
```

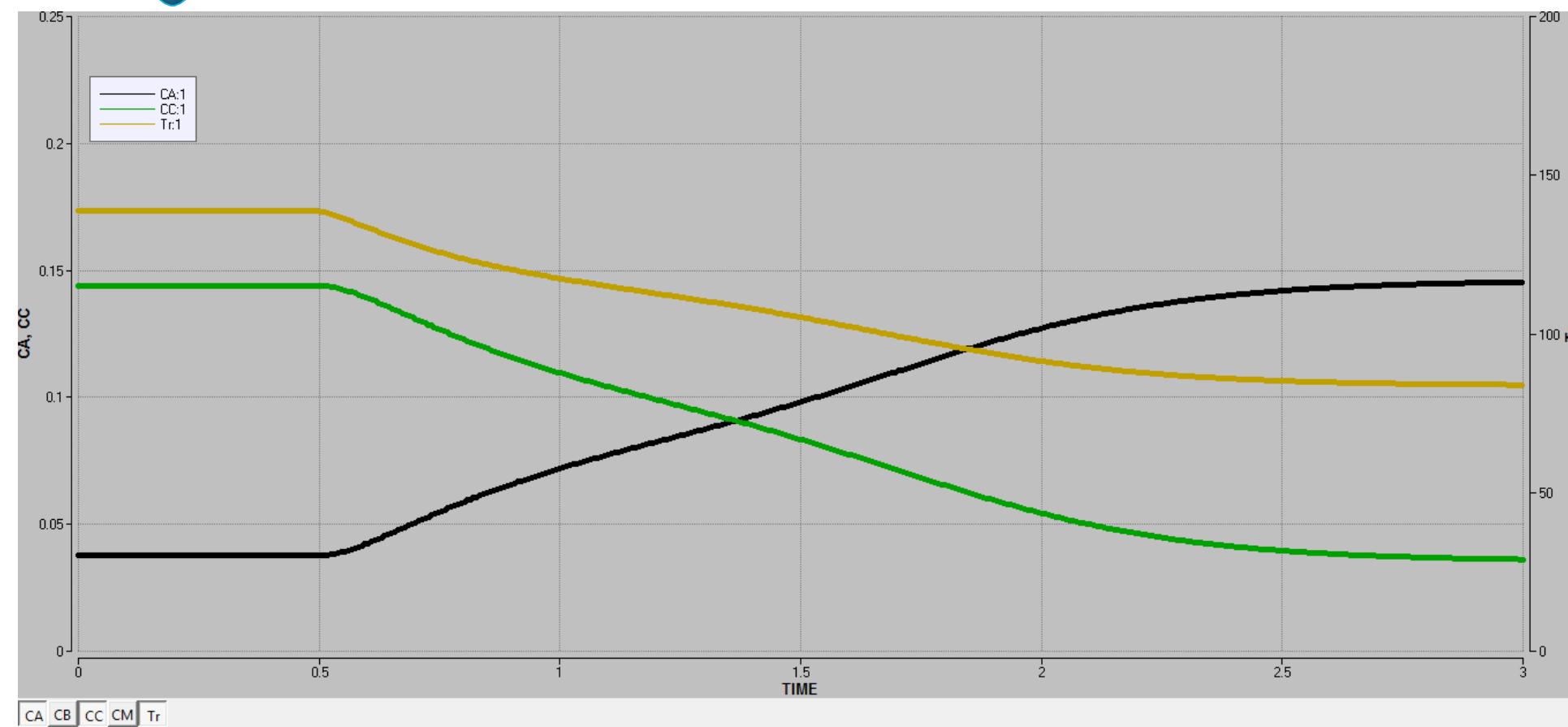
```
PMs = 18
```

```
DPs = 4.383E11
```

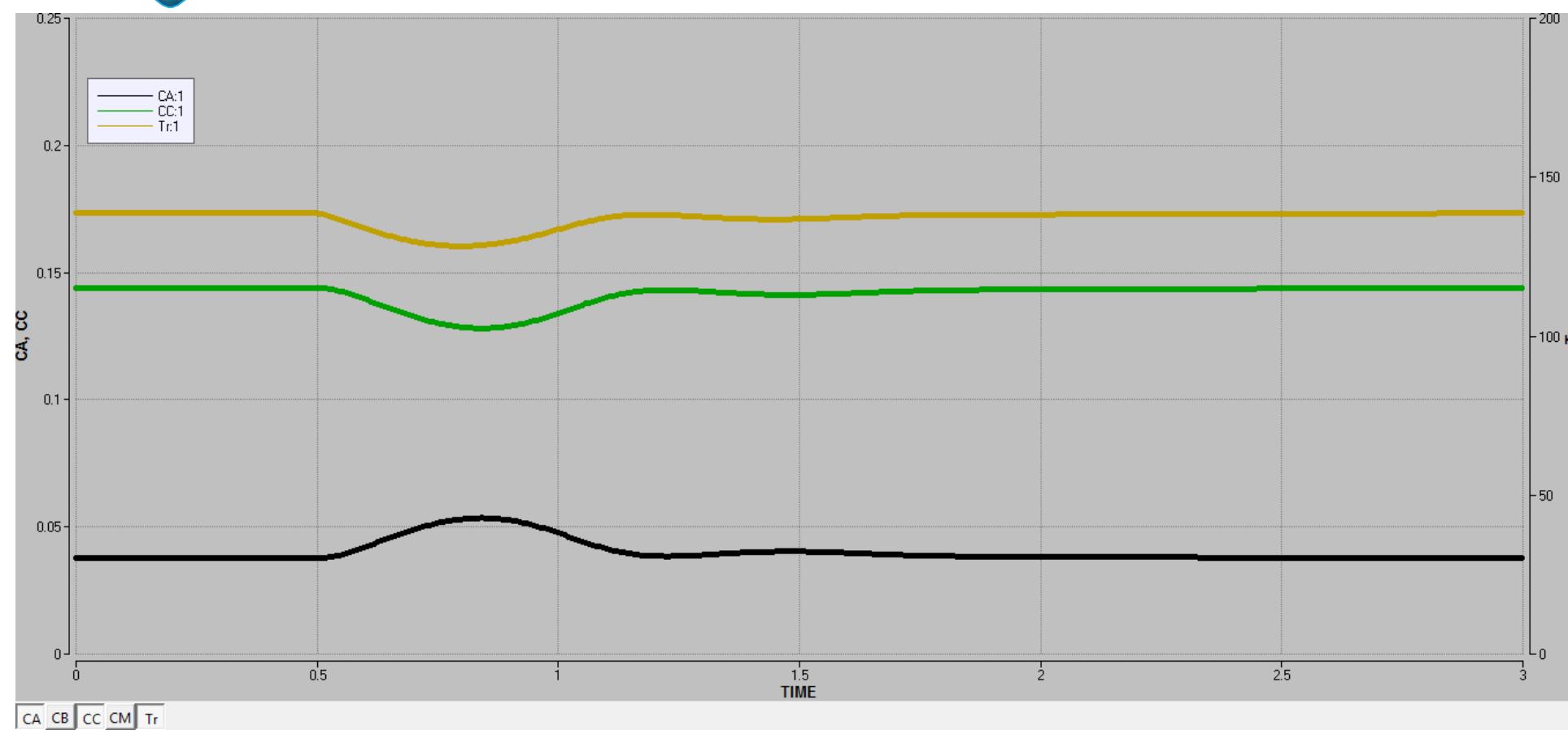
```
Cvs = 8.71E-4
```

Ver Reactor con CT.mmd

$\text{Sin CT}, T_0 = 75 - \text{step}(5,0.5)$



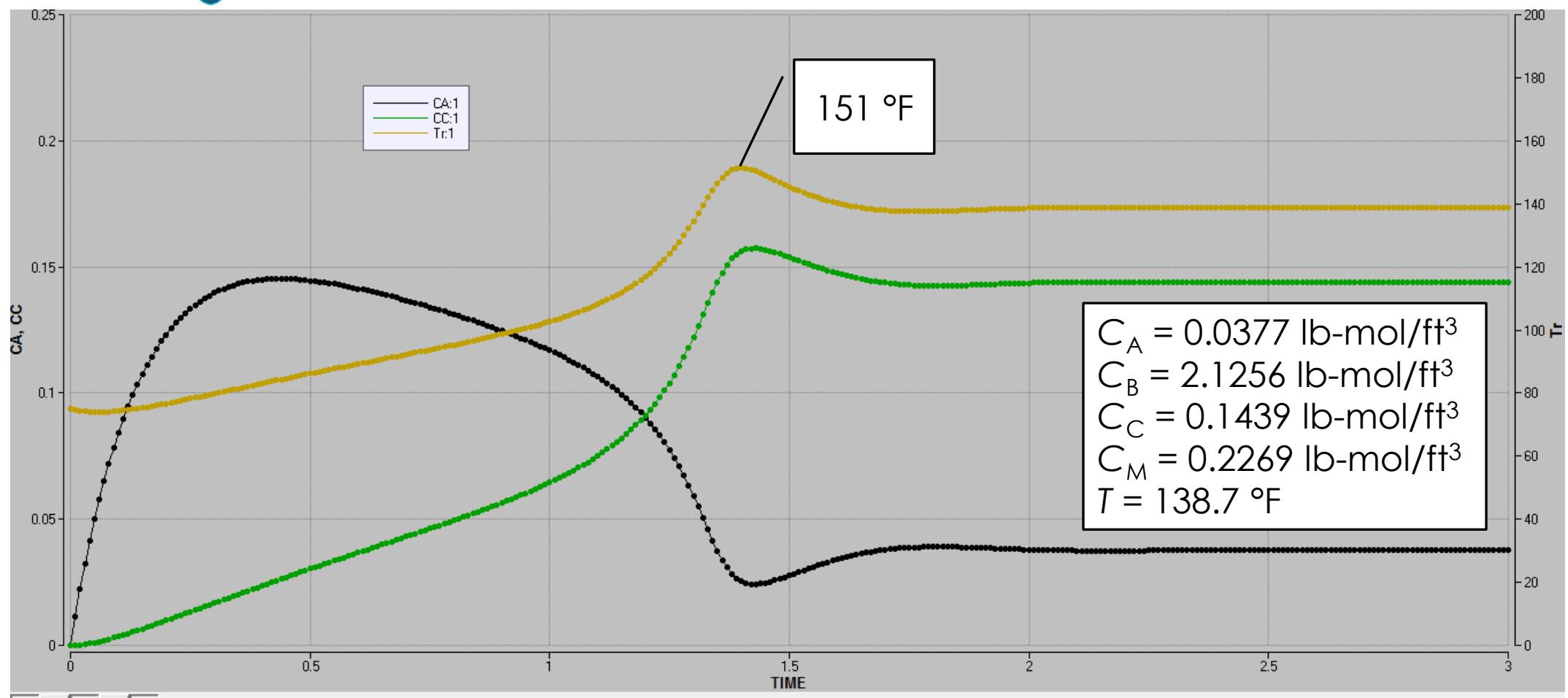
Con CT, $T_0 = 75 - \text{step}(5,0.5)$



Puesta en marcha sin CT

- Inicialmente, agua a 75° F.
- Serpentín funcionando.
- $C_A = 0 \text{ lb-mol/ft}^3$
- $C_B = 3.45 \text{ lb-mol/ft}^3$
- $C_C = 0 \text{ lb-mol/ft}^3$
- $C_M = 0 \text{ lb-mol/ft}^3$
- $T = 75 \text{ }^{\circ}\text{F}$
- $K_p = 0 \text{ }^{\circ}\text{F}^{-1}$

Puesta en marcha sin CT



Puesta en marcha con CT

- Inicialmente, agua a 75° F.
- Serpentín funcionando.
- $C_A = 0 \text{ lb-mol/ft}^3$
- $C_B = 3.45 \text{ lb-mol/ft}^3$
- $C_C = 0 \text{ lb-mol/ft}^3$
- $C_M = 0 \text{ lb-mol/ft}^3$
- $T = 75 \text{ }^\circ\text{F}$
- $K_p = 4.25 \times 10^{-3} \text{ }^\circ\text{F}^{-1}$
- $x_{\min} = 1 \times 10^{-4}$

Puesta en marcha con CT

